

CONCEPT QUICKSTART – Equation of a Line in Space

Unit: Unit 11: Three Dimensional Geometry

Subject: CBSE Class 12 Mathematics

SECTION 1: UNDERSTANDING THE CONCEPT

1.1 What Is Equation of a Line in Space?

In our 3D world, a line is uniquely fixed if we know two simple things: where it starts (a point) and where it's going (its direction). Think of it like a laser pointer in a dark room. To know exactly where that beam of light is, you need to know the location of the pointer and the direction you are aiming it.

While we use **Vectors** to make our calculations look "elegant" and simple, we often switch to **Cartesian forms** to help us "visualize" the line on a coordinate grid. It is important to remember that in 3D, a line isn't just one equation like $y = mx + c$. Because we have three dimensions (x, y, and z), the equation is actually a system of ratios or a vector path where every point follows a specific direction.

1.2 Why It Matters

This topic is the bridge that turns abstract vectors into actual physical paths in space. It is strategically vital because it connects everything you learned in Chapter 10 (Vectors) to real-world geometry. By mastering these equations, you gain the power to find the distance between airplanes in flight or calculate angles in engineering and physics.

1.3 Prior Learning Connection

To make this easy, make sure you remember these "tools" from earlier chapters:

- **Vectors (Ch 10):** Especially position vectors (a) and direction vectors (b).
- **Direction Cosines/Ratios:** These are just the numbers (a, b, c) that tell us which way the line is leaning.
- **2D Lines (Class 11):** The basic idea that every line needs a point and a "slope" (direction).

1.4 Core Definitions

Note: Use these formulas to match the specific "Problem Type" in your exam.

Item Label	NCERT Reference	Formula (Unicode)	Problem Type

Vector Equation (One Point)	Sec 11.3.1	$r = a + \lambda b$	Given a point (a) and a parallel vector (b).
Cartesian Equation (One Point)	Sec 11.3.1	$(x - x_1) / a = (y - y_1) / b = (z - z_1) / c$	Standard form using point (x_1, y_1, z_1) and direction ratios a, b, c.
Vector Equation (Two Points)	Sec 11.3.2	$r = a + \lambda(b - a)$	Used when only two points (a and b) are provided.
Cartesian Equation (Two Points)	Sec 11.3.2	$(x - x_1)/(x_2 - x_1) = (y - y_1)/(y_2 - y_1) = (z - z_1)/(z_2 - z_1)$	Finding the line path directly from two coordinate sets.

SECTION 2: WHAT NCERT SAYS

2.1 Key Statements

Based on NCERT Section 11.3, here is what you need to know for your theory marks:

- Uniqueness:** A line is only "locked" in space if it passes through one point with a fixed direction, or if it passes through two specific points.
- The Role of λ :** Don't let the Greek letter scare you! λ (lambda) is just a "sliding scale" or parameter. As λ changes, the formula points to every single point on that infinite line.
- Vector to Cartesian:** You can move between forms easily. Just substitute $r = x\hat{i} + y\hat{j} + z\hat{k}$ into the vector equation and separate the x, y, and z parts.
- Direction Ratios:** In the Cartesian form, the numbers in the "basement" (the denominators a, b, c) are the direction ratios of the line.

2.2 Examples and Exercises

If you are short on time, prioritize these specific NCERT problems:

NCERT Reference	Focus Area	Why it's Important
Example 6 (Pg 382)	Vector & Cartesian Basics	Shows the step-by-step conversion from point/vector to equations.
Example 7 (Pg 384)	Angle Calculations	A frequent exam favorite; uses the dot product of direction vectors.
Exercise 11.2 (Q4-Q7)	Equation Drafting	The "bread and butter" of 3D geometry exams.

Exercise 11.2 (Q8–Q11)	Angle Mastery	Crucial for scoring those 2–3 mark "short answer" questions.
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SECTION 3: PROBLEM-SOLVING AND MEMORY

3.1 Problem Types

Problem Type: Line through Point & Parallel to Vector (Family F4)

- **Recognition Cues:** Look for "passes through point P" and "parallel to vector b."
- **The Big Idea:** Think of this as the "**Anchor and the Beam.**" The point **a** is your **Anchor** (where the line is held), and the vector **b** is your **Beam** (the direction you are aiming).

Problem Type: Line through Two Points (Family F5)

- **Recognition Cues:** Wording like "find equation of line passing through A and B."
- **The Big Idea:** You are using the difference between two points to create your own direction beam.

Problem Type: Show Points are Collinear (Family F3)

- **Recognition Cues:** "Show that points (x, y, z) , (x, y, z) , and (x, y, z) are collinear."
- **The Big Idea:** You just need to show that the direction ratios between point A-B and point B-C are proportional (they have the same "slope").

3.2 Step-by-Step Methods

Don't worry about the letters—just follow these baby steps for the **Point and Parallel Vector** type:

1. **[Pre-Check]:** Make sure your direction vector **b** isn't zero. A line has to point somewhere!
2. **[Setup]:** Identify the position vector **a** (the Anchor point) and the direction vector **b** (the Beam).
3. **[Apply]:** Plug them into the pattern $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$. (Think of λ as a sliding scale that moves you along the beam).
4. **[Transform]:** To get Cartesian form, put the point's coordinates in the top (numerators) and the direction numbers in the bottom (denominators): $(x - x_1) / a = (y - y_1) / b = (z - z_1) / c$.

⚠ STOP! When NOT to use this: If the problem gives you two points but *no* direction vector, don't force it! Use the **Two-Point Method** instead.

3.3 How to Write Answers for Full Marks

CBSE examiners love structure. Use this "Mock Answer Frame" to guarantee your marks:

CBSE MOCK ANSWER BOX
Given: Point $A = (x_1, y_1, z_1)$ and Parallel Vector $\mathbf{b} = a\hat{i} + b\hat{j} + c\hat{k}$.
Step 1: The position vector of the given point is $\mathbf{a} = x_1\hat{i} + y_1\hat{j} + z_1\hat{k}$.
Step 2: The direction vector is $\mathbf{b} = a\hat{i} + b\hat{j} + c\hat{k}$.
Step 3: We know the vector equation of a line is $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$.
Step 4: Substituting the values: $\mathbf{r} = (x_1\hat{i} + y_1\hat{j} + z_1\hat{k}) + \lambda(a\hat{i} + b\hat{j} + c\hat{k})$.
Essential Phrases: "Let r be the position vector of any point $P(x, y, z)$ on the line, where λ is a real parameter ($\lambda \in \mathbb{R}$)."

3.4 Common Mistakes

Pitfall	Why it's Wrong	✓ The Fix
Swapping a and b	Using the direction as the point.	Remember: a is the Anchor (point), b is the Beam (direction).
Sign Errors	Writing $(x + 5)$ for point 5.	The formula has a minus: $(x - x_1)$. A point at +5 becomes $(x - 5)$.
Missing $\lambda \in \mathbb{R}$	Forgetting the parameter's set.	Always write " $\lambda \in \mathbb{R}$ " at the end of your vector equation.

3.5 Exam Strategy

Mastering the **conversion between Vector and Cartesian forms** is your secret weapon. If you can switch between them fluently, you can solve almost any 2-3 mark question in seconds.

3.6 Topic Connections

Mastering the line opens the door to:

- **Shortest Distance (Sec 11.5):** Finding the gap between two "Skew Lines" (lines that never touch and aren't parallel).
- **Equation of a Plane (Sec 11.6):** Taking your 1D line knowledge and applying it to 2D flat surfaces in space.

3.7 Revision Summary

1. **Vector Algebra in 3D:** We use vectors because they make complex 3D math look simple and elegant.
2. **The 3D System:** Every point is a triplet (x, y, z) relative to three perpendicular axes.
3. **Dual Representation:** Every result in this chapter exists in two "flavors": Vector and Cartesian.
4. **Direction Angles:** α , β , and γ are the angles the line makes with the x , y , and z axes.
5. **Direction Cosines:** These are l , m , and n . They are unique and *always* satisfy $l^2 + m^2 + n^2 = 1$.
6. **The Bridge:** Vector methods reduce messy algebra; they are the bridge to spatial intuition.
7. **Foundation:** DC and DR (Direction Ratios) are the "DNA" of every line and distance calculation.
8. **Geometric Intuition:** Visualization is key—don't just memorize, try to see the "Anchor and the Beam" in your head.

Memory Aid: In Cartesian form, the **Point** is in the Numerator (always change the sign because the formula is $x - x_1$) and the **Direction** is always in the Denominator!

Teacher's Encouragement: See? It's just like 2D math, but with one extra coordinate. Once you see the pattern, you can't un-see it. You're going to do great! 🙌 📦 ✨

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